

# Learning Determinantal Point Processes



## Using Moments and Cycles

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### I. INTRODUCTION

#### Definitions: DPP

- A **determinantal point process** (DPP)  $Y \subseteq [N]$  is a random subset s.t.

$$\mathbb{P}[Y \subseteq Y] = \det(K_J), \forall J \subseteq [N]$$

for some symmetric matrix  $K \in \mathbb{R}^{N \times N}$  s.t.  $0 \leq K \leq I_N$ .

- Ex:  $\mathbb{P}[1 \in Y] = K_{1,1}$ ,  $\mathbb{P}[1,2 \in Y] = K_{1,1}K_{2,2} - K_{1,2}^2$ .

- If  $K < I_N$ , the DPP( $K$ ) is also an **L-ensemble**:

$$\mathbb{P}[Y = J] = \frac{\det(L_J)}{\det(I_N + L)}, \quad \forall J \subseteq [N]$$

where  $L = K(I_N - K)^{-1}$  ( $\Leftrightarrow K = L(I_N + L)^{-1}$ ).

- Alternative representation:  $(X_1, X_2, \dots, X_N) \in \{0,1\}^N$ , where  $X_j \in Y \Leftrightarrow j \in Y$ .

- DPPs can model repulsive interactions:  $(X_1, X_2, \dots, X_N)$  are **negatively associated** ( $\gg$  negative correlation), i.e.,

$$\text{cov}(f(X_i, i \in S), g(X_j, j \in T)) \leq 0,$$

for all disjoint  $S, T \subseteq [N]$  and coordinatewise nondecreasing functions  $f, g$ .

E.g.,  $\text{cov}(X_i, X_j) = -K_{i,j}^2 \leq 0$ .

#### Learning objective

Given i.i.d. copies  $Y_1, Y_2, \dots, Y_n \sim \text{DPP}(K)$  with unknown kernel, estimate  $K$ .

#### Identifiability of $K$

$$\begin{aligned} \text{DPP}(K) = \text{DPP}(K') &\Leftrightarrow \det(K_J) = \det(K'_J), \forall J \subseteq [N] \\ &\Leftrightarrow K' = DKD, \text{ for some } D = \\ &\quad \text{Diag}(\pm 1, \dots, \pm 1). \end{aligned}$$

⇒ **Principal minor assignment problem** [RKT15]: Find all symmetric matrices that have a prescribed list of principal minors.

### II. Method of Moments

- First step:  $K_{i,i} = \mathbb{P}[i \in Y] \rightsquigarrow \widehat{K}_{i,i} = \frac{1}{n} \sum_{k=1}^n \mathbf{1}_{i \in Y_k}$
- Second step:  $K_{i,j}^2 = K_{i,i}K_{j,j} - \mathbb{P}[i, j \in Y]$
- $\rightsquigarrow \widehat{K}_{i,j}^2 = \left( \widehat{K}_{i,i}\widehat{K}_{j,j} - \frac{1}{n} \sum_{k=1}^n \mathbf{1}_{i,j \in Y_k} \right)^+$
- Third step: Recover the signs

#### Determinantal graph:

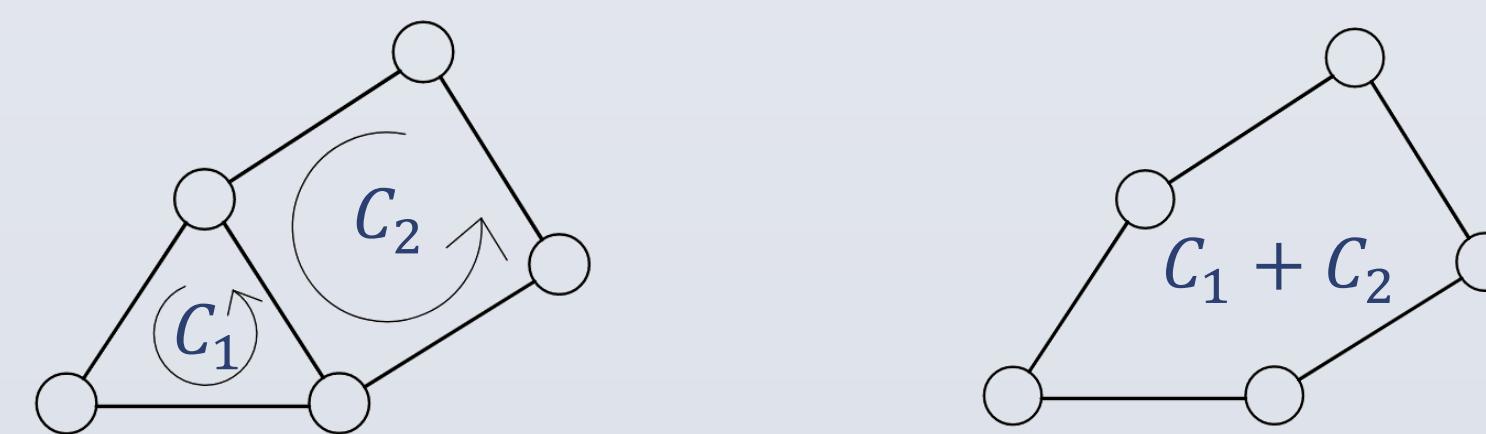
**Definition 1.1:**  $G = ([N], E)$ , with  $E_K = \{(i, j) : K_{i,j} \neq 0\}$ .

$$K = \begin{pmatrix} * & * & 0 \\ * & * & * \\ 0 & * & * \end{pmatrix} \quad \begin{array}{c} \text{Graph:} \\ \text{---} \end{array} \quad \begin{array}{c} \text{Graph:} \\ \text{---} \end{array}$$

$$K = \begin{pmatrix} * & * & * & 0 \\ * & * & * & 0 \\ * & * & * & * \\ 0 & 0 & * & * \end{pmatrix} \quad \begin{array}{c} \text{Graph:} \\ \text{---} \end{array} \quad \begin{array}{c} \text{Graph:} \\ \text{---} \end{array}$$

#### Cycle Sparsity

**Cycle basis:** family of *induced cycles* that span the cycle space



**Cycle sparsity:** length  $\ell$  of the largest cycle needed to span the cycle space

**Horton's algorithm:** Find a cycle basis with cycle lengths  $\leq \ell$  in  $O(|E|^2 N (\ln N)^{-1})$  steps [Horton '87; Amaldi *et al.* '10]

**Theorem:**  $K$  is completely determined, up to  $\mathcal{D}$ -similarity, by its principal minors of order  $\leq \ell$ .

**Key idea:** Find the sign of  $\prod_{\{i,j\} \in C} K_{i,j}$  for each cycle of length  $\leq \ell$ , using the corresponding principal minors.

### III. ALGORITHM

**Assumption:**  $K \in \mathcal{K}_\alpha$ , i.e., either  $K_{i,j} = 0$  or  $|K_{i,j}| \geq \alpha$ , for some known  $\alpha \in (0,1)$ .

- All  $K_{i,i}$ 's and  $|K_{i,j}|$ 's are estimated within  $n^{-1/2}$ -rate
- $G$  is recovered exactly w.h.p.
- **Horton's algorithm** outputs a minimum basis  $\mathcal{B}$
- For all induced cycle  $C \in \mathcal{B}$

$$\det K_C = F_C(K_{i,i}, K_{i,j}^2) + 2(-1)^{|C|} \prod_{\{i,j\} \in C} K_{i,j}$$

⇒ Recover the sign of  $\prod_{\{i,j\} \in C} K_{i,j}$  w.h.p.

Remark:  $\left| \prod_{\{i,j\} \in C} K_{i,j} \right|$  may be as small as  $\alpha^\ell \hookrightarrow$  finding its sign requires  $\Omega(\alpha^{-2\ell})$  samples.

### IV. MAIN RESULTS

#### Upper bound:

**Theorem:** Let  $K \in \mathcal{K}_\alpha$  with cycle sparsity  $\ell$  and let  $\varepsilon > 0$ . Then, the following holds with probability at least  $1 - n^{-4}$ :

There is an algorithm that outputs  $\widehat{K}$  in  $O(|E|^3 + nN^2)$  steps for which

$$n \gtrsim \left( \frac{1}{\alpha^2 \varepsilon^2} + \ell \left( \frac{2}{\alpha} \right)^{2\ell} \right) \ln N \Rightarrow \min_D \|\widehat{K} - DKD\|_\infty \leq \varepsilon$$

#### Lower bound:

#### Theorem:

Let  $0 < \varepsilon \leq 1/8$  and  $3 \leq \ell \leq N$ . There exists  $C > 0$  such that if

$$n < C \left( \frac{8^\ell}{\alpha^{2\ell}} + \frac{\ln \left( \frac{N}{\ell} \right)}{(6\alpha)^\ell} + \frac{\ln N}{\varepsilon^2} \right)$$

then the following holds:

For any estimator  $\widehat{K}_n$ , there exists  $K \in \mathcal{K}_\alpha$  with cycle sparsity  $\ell$  and for which  $\min_D \|\widehat{K}_n - DKD\|_\infty > \varepsilon$  with probability at least  $1/3$ .

### V. CONCLUSION AND OPENING

#### REMARKS

- Estimation of  $K$  by a method of moments in **polynomial time**
- Rates of estimation characterized by the topology of the determinantal graph through its **cycle sparsity  $\ell$** .
- These rates are provably **optimal** (up to logarithmic factors)
- **Adaptation** to  $\ell$ .
- Another estimator, obtained by a **maximum likelihood approach**, does not assume separation of the nonzero entries of  $K$  and achieves the rates  $n^{-1/2}$  or  $n^{-1/6}$ , depending on the connectedness of  $G$  [BMRU17-a,b].

### REFERENCES

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